

# **Automatic Weigh Filler**

User's Manual

Model no.: AF-50K-103A

## Contents

| 1. Info                 | 1 -  |
|-------------------------|------|
| 1.1 Characteristics     | 1 -  |
| 1.2 Specification       | 1 -  |
| 1.3 Structure           | 2 -  |
| 2. Dimensions           | 3 -  |
| 2.1 Appearance          | 3 -  |
| 2.2 Flang size          | 4 -  |
| 2.3 Sketch              | 4 -  |
| 3. Installation         | 5 -  |
| 3.1 Warranty            | 5 -  |
| 3.2 Warning notics      | 5 -  |
| 3.3 Connection          | 6 -  |
| 3.3.1 Load cell         | 6 -  |
| 3.3.2 Air vent          | 7 -  |
| 3.3.3 Serial port       | 8 -  |
| 4. Operation            | 12 - |
| 4.1 Menu                | 12 - |
| 4.2 Main menu           | 13 - |
| 4.3 Login               | 13 - |
| 4.4 User management     | 14 - |
| 4.5 Parameter configure | 15 - |
| 4.5.1 System parameter  | 15 - |
| 4.5.2 User parameter    | 18 - |
| 4.5.3 Batch parameter   | 18 - |
| 4.6 Calibration         | 19 - |
| 4.6.1 Calibration-1     | 19 - |
| 4.6.2 Calibration-2     | 21 - |
| 4.7 I/O                 | 21 - |
| 4.7.1 Input define      | 22 - |
| 4.7.2 Output define     | 22 - |
| 4.7.3 Input test        | 23 - |
| 4.7.4 Output test       | 23 - |

| 4.8 Peripheral device      | - 24 - |
|----------------------------|--------|
| 4.8.1 Level sensor         | 24 -   |
| 4.8.2 Clipper              | 25 -   |
| 4.8.3 Code printer         | 25 -   |
| 4.8.4 Printer              | 25 -   |
| 4.9 Data statistics        | 27 -   |
| 4.10 System function       | 27 -   |
| 4.10.1 Firmware update     | 27 -   |
| 4.10.2 Backup and reset    | 28 -   |
| 4.10.3 Output to USB       | 28 -   |
| 4.10.4 USB input           | 28 -   |
| 5. Procedure               | 29 -   |
| 5.1 Procedure              | 29 -   |
| 5.2 Self-adaptive function | 29 -   |
|                            |        |



## 1. Information

The Weigh Filler AF-50K-103A is the perfect all-round weighing machine to fill sensitive granules from 5kgs to 50kgs, such as rice, bean, maize, seed etc. It is very flexible and applicable for very different products and it reaches a filling speed of 18 fillings per minute with just one weighing head. Underfeeding is impossible with the self-controlled weighing machine. This guarantees both satisfied customers and minimum product loss.

### 1.1. Characteristics

- Weighing capacity from 5kgs to 50kgs
- High visibility 4.3 inch TFT screen with graphic user interface
- Weigh products precisely without inputting various setting
- Automatic weighing compensation and zero tracking
- 50,000pcs weight value for production statistics
- Data storage and data printout ready
- Access protection by password

### **1.2. Specification**

| Model no.               | AF-50K-103A           |
|-------------------------|-----------------------|
| Weighing Range:         | 5~50kgs               |
| Accuracy:               | ±10g                  |
| Weighing Hopper Volume: | 30L                   |
| Operation Air Pressure: | 0.4~0.6Mpa, 1.2m³/h   |
| Power Supply:           | AC110~260V,50~60Hz    |
| Dimensions(L x W x H):  | 815mm x 730mm x 790mm |
| Operating Temperature   | -10°C~40°C            |
| Relative Humidity       | 90% R.H. Without dew  |

### 1.3. Structure

The Weigh Filler AF-50K-103A are specially designed for sensitive granules, which are easy to integrate in packaging equipment.



- 1. Junction box
- 2. Load cell
- 3. Lifting eyebolt
- 4. Dust removing flange
- 5. Weighing hopper
- 6. Filling hopper
- 7. Cylinder control box
- 8. Air vent
- 9. Load cell
- 10. Electronic Control box

Note: The user need take off the cover of dust removing flange first, then connect with the tube to remove inside dust.

## 2. Dimension

## 2.1. Outward appearance



## 2.2. Flange size



## 2.3. Installation diagrammatic sketch



## 3. Installation

### 3.1. Warranty

We do not accept any liability for damages resulting from:

- 1) Non-compliance with our operating conditions and user's manual.
- 2) Unauthorized installation.
- 3) Defective electrical installation by the customer.
- 4) Structural changes to our equipment.
- 5) Incorrect operation.
- 6) Natural wear and tear.

### 3.2. Warning notice

The main switch must be off in the following situations:

1) Before carrying out work in the control cabinet, cut off power and disconnect the power connector.

2) When cleaning and maintenance work is being carried out on the outside of the control cabinet.

3) Risk to life from an electrical charge in the control cabinet.

The device must be operated by people who have been instructed in the operating procedure.

The operator must understand the safety instructions in this manual.

Even though the device is equipped with all the required safety installations, injuries to the operating personnel or damage to property is possible if the safety instructions are not heeded.

## 3.3. Connection

### 3.3.1 Load cell

Please take off the screws on the protection boards which protect load cells to avoid damage in delivery



Side view-1





Note: 1. Please install load cells after the weigh filler has been fixed on equipment.

2. Please fasten the screws when load cell connection and weighing device are in nature.



### 3.3.2 Air vent

Operation air pressure: 0.4~0.5Mpa, 1.2m3/h

### 3.3.3 Serial port

IO terminals:



### 1). Serial port 1 (GND\_UART、U0\_A、U0\_B) connection:

RS485/RS232 optional by SW1 and SW2 on main board: SW1 to left and SW2 up for RS485 communication, and SW1 to right and SW2 down for RS232 communication.



RS232 connection:



RS485 connection:



2). Serial port2 (GND\_UART, U3\_A, U3\_B) : Only RS485 connection



#### 3). (OUT6A、OUT6B) – (OUT12A、OUT12B)

The user can refer parameter chapter to self-define 7pcs outputs.

Controller output schematic as follows. **OUT1~OUT5** are set by manufactory, so the user don't need to connect and define.



#### 4). IN1–IN12:

The user can refer parameter chapter to self-define 12pcs Inputs at active low. Controller input schematic as follows.



5). **24V+**, **GND:** The terminal supply one DC24V power, which positive connect with indicator 24V+, negative electrode with indicator GND.

### 3.4. LED instruction



There are five LED lights named LED1~5 from the left to the right.

All of LED1~5 bright means the controller is updating within 4 seconds.

LED state instruction:

- LED1: Sparkle interval time is one second. If not, the controller will have problems.
- LED2: Bright for running. If not, the controller will stop.
- LED3: Bright for error in A/D convert module. If it is dark, the A/D convert module is OK.
- LED4: Bright for serial port no. 1 to send data.
- LED5: Bright for serial port no. 2 to send data.

## 4. Operation

### 4.1. Menu



Instruction:

Load information: User level.

(2) System time and date: Current time and date.

- (3) Weight display: Show weight value and unit.
- (4) Stable sign: Green sign for stable and white sign for unstable.
- (5) Zero sign: Green sign for zero and white sign for not zero.
- (6) Procedure: Run/Stop, Coarse, Fine, Stable load, Discharge, Over and Under, Clip bag.

⑦ Data: The left side is current recipe data which can be revised by users. The right side show statistics and last packing data.

(8) Function: 5pcs keys for system function.

Key function:



### 4.2. Main menu



### 4.3. Login

The default administrator ID is 12345678 and password is 000000. Please change the password to use for first time. For other users, please refer"User management"

|                    |          | NON          | E 0 - 0<br>0:00 |   |
|--------------------|----------|--------------|-----------------|---|
| →0+<br>Stop Coarse | <br>Fine | STBL DISC 08 | U Clip          |   |
| Target:            | 0        | Lack feed:   | 0               | 1 |
| CRS feed:          | 0        | Total Time:  | 0.000           |   |
| Fe11.              | 0        | CRS Food T.  | 0 000           |   |

|           |          | (Michael              |
|-----------|----------|-----------------------|
| User ID:  | 12345678 | Rights : Administrato |
| Password: |          |                       |
|           | Login    |                       |
|           |          | DReturn               |

### 4.4. User management

### User

Press Management to register authorization levels: Manufactory, System administrator, Administrator, Technician, Operator.



Level explanation:

| User<br>Menu           | Manufactory  | System<br>administrator | Administrator | Technician   | Operator     |
|------------------------|--------------|-------------------------|---------------|--------------|--------------|
| Parameter<br>Configure | $\checkmark$ | $\checkmark$            | $\checkmark$  | $\checkmark$ | $\checkmark$ |

| Calibration          | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
|----------------------|--------------|--------------|--------------|--------------|--------------|
| Help                 | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| User<br>management   | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| Data<br>Statistics   | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | ×            |
| I/O Configure        | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | ×            |
| Peripheral<br>Device | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | ×            |
| System<br>Function   | $\checkmark$ | $\checkmark$ | $\checkmark$ | ×            | ×            |
| Manufactory          | $\checkmark$ | ×            | ×            | ×            | ×            |

### 4.5. Parameter Configure

Parameter Configure to set System Parameter, User Parameter and Batch Parameter. Parm Configure 0.788Kg A-Level System Parameter User Parameter Batch Parameter Main Centre

### 4.5.1 System parameter

| No. | Parameter     | Range                               | Initial | Instruction          |
|-----|---------------|-------------------------------------|---------|----------------------|
| 1   | Unit          | g Kg t lb                           | Kg      | System unit          |
| 2   | Decimal point | 0<br>0.0<br>0.00<br>0.000<br>0.0000 | 0.000   | System decimal point |
| 3   | Mini division | 1 / 2 / 5 / 10<br>/ 20 / 50         | 1       | Mini division        |

| 4  | Max. capacity                                  | xxxxxx   | 100.000      | Max. capacity   |
|----|--|--|--------------|---|
| 5  | Work mode                                      | Single   | Single       | Single scale  |
| 6  | Automatic<br>zeroing<br>interval               | 0~999999   | 80           | Zeroing after some packing times. Not to zero If 0.<br>Note: Not to zero for first packing. |
| 7  | Zeroing<br>range                               | 1%~99%   | 10%          | 1%~99% of max. capacity.  |
| 8  | Stable range                                   | 0~99   | 5            | 0~99d optional.<br>Stable state will be continue if 0.                                      |
| 9  | Stable time                                    | 0.001~   | 0.3 s        | Stable weight within stable time, otherwise unstable.                                       |
| 10 | Zero tracking<br>range                         | 0~9  | 3            | 0~9d optional<br>Not to track zero if 0.  |
| 11 | Zero tracking<br>time                          | 0.001~9.999  | 2 s          |   |
| 12 | Running AD filter grade                        | 0~9  | 2            | The bigger the stronger   |
| 13 | Stop AD filter grade                           | 0~9  | 9            | The bigger the stronger   |
| 14 | Automatic<br>zeroing<br>switch                 | ON/OFF   | OFF          | Zeroing or not when power supply is on.   |
| 15 | Manual<br>discharging<br>switch                | ON/OFF   | OFF          | Account to total or not for manual discharging.   |
| 16 | Fix weight<br>display switch                   | ON/OFF   | OFF          | After meeting target weight, the value will be displayed continuously till discharging.     |
| 17 | Automatically<br>adjust filling<br>door switch | ON/OFF   | ON           | Adjustable  |
| 18 | Screen bright<br>time                          | Bright /<br>10 minute /<br>5 minutes /<br>1 minute | 5<br>minutes |   |
| 19 | Language                                       | Chinese /<br>English                               | Chinese      | Operation language  |

#### Self-adjustable parameter:

| No. | Parameter | Initial | Instruction   |  |
|-----|-----------|---------|---|--|
| 1   | ON/OFF    | ON      | Self-adjustable coarse filling and fine filling switch  |  |
| 2   | 0~10      | 0       | Packing speed grade.<br>0 is normal. The bigger the slower, but higher precision.   |  |
| 3   | ON/OFF    | OFF     | Positive deviation function switch<br>ON : The weighing result will be positive deviation<br>compared with target value in filling.<br>OFF: The weighing result will be positive or minus around<br>0 in filling. |  |

#### Date and time

Press

System Parameter

to check date & time or change setting, then confirm if changed.

### Communication parameters for serial port 1 and 2:

| No. | Parameter  | Initial    | Instruction              |
|-----|--|------------|--------------------------|
| 1   | 1~99   | 1          | ID code                  |
| 2   | Modbus-RTU /<br>Modbus-<br>ASCII/Printer                 | Modbus-RTU | Communication parameters |
| 3   | 9600、<br>19200、<br>38400、<br>57600、<br>115200、<br>256000 | 38400      | Baud rate                |
| 4   | 1-8-NONE-2、<br>1-8-EVEN-1、<br>1-8-ODD-1、                 | 1-8-EVEN-1 | Data format              |

|   | 1-8-NONE-1              |          |               |
|---|-------------------------|----------|---------------|
| 5 | High-low / Low-<br>high | High-low | Register data |

### Ethernet parameters:

| No. | Parameter               | Initial    | Instruction            |
|-----|-------------------------|------------|------------------------|
| 1   | Modbus-TCP              | Modbus-TCP | Communication protocol |
| 2   | High-low / Low-<br>high | High-low   | Register data          |
| 3   | 0~65535                 | 502        | ID                     |
| 4   | xxx.xxx.xxx.xxx         | 0.0.0.0    | IP address             |
| 5   |                         |            | MAC address            |

### 4.5.2 User parameter

The user can set 20 set recipes parameters as follows:

| No. | Parameter         | Initial | Instruction   |
|-----|-------------------|---------|---|
| 1   | 1~20              | 1       | Recipe no.  |
| 2   | хххххх            | 0       | Target value  |
| 3   | хххххх            | 0       | Leading quantity of coarse feeding. When present weight<br>≥ Target value-Leading quantity of coarse feeding, and then shut off coarse feeding. |
| 4   | хххххх            | 0       | Free fall value. When present weight ≥ target value-free fall value, and then shut off the fine feeding.  |
| 5   | $0{\sim}99.999$ s | 0.3 s   | Discharge time<br>Output discharging signal within effective time.  |
| 6   | ON/OFF            | OFF     | Over / under tolerance switch   |
| 7   | xxxxxx            | 0       | Over tolerance<br>Present weight ≥ target value + over value.   |
| 8   | хххххх            | 0       | Under tolerance<br>Present weight ≤ target value - under value.   |
| 9   | 0∼99.999 s        | 2 s     | Alarm time for over/under tolerance   |

|    |                   |       | Pause switch for over/under tolerance  |
|----|-------------------|-------|--|
| 10 | ON/OFF            | OFF   | <b>ON:</b> Stop. The user can press "Clear alarm" to go on or press "E-Stop" to stop running.                      |
|    |                   |       | <b>OFF</b> : Just output alarm signal, not stop.   |
| 11 | 0~99              | 1     | Single weighing times<br>Weigh once to discharge for packing. If 0, it will directly<br>discharge with bag or not. |
| 12 | $0{\sim}99.999$ s | 0 s   | Delay time before filling<br>Begin to fill material after delay time <b>t1.</b>                                    |
| 13 | 0∼99.999 s        | 0.9 s | Fix weight time.<br>Output discharging signal after this time when filling has<br>finished.                        |

#### 4.5.3 Batch parameter

Batch Parameter

to set batching times. The device will pause to

output alarm signal after finished, then the user can clear alarm by pressing "Clear alarm", " Stop" or " E-Stop".

### 4.6. Calibration

The user can press

The user need calibrate AF-50K-103A to use for first time or any change or weighing error.



Note: The user can calibrate by standard weight or filling material.

#### 4.6.1 Calibration with standard weight

1) Zero calibration: Empty hopper and press "Zero calibration" to display zero on screen.

Then device will enter gain calibration automatically after zero calibration has been finished 2 seconds later.

| Calibrate Zero   | ► 6   | 1.3Kg | A-Level  |  |  |  |  |
|--|---|-------|----------|--|--|--|--|
| [Empty the weighing hopper and wait ur<br>press "Zero CAL" button. If succeed,<br>will appear automatically after 2 second<br>name on the left top will changes, pleas | ntil it is stable, then<br>"Calibrate Weight" Page<br>Is and the page<br>e note.] |       |          |  |  |  |  |
| Loadcell Voltage : 0.0   | 00mV  |       |          |  |  |  |  |
| Zero CAL   |   |       |          |  |  |  |  |
| 🖻 Main   | Calibrate weight  |       | 🕽 Return |  |  |  |  |

2) Gain calibration: Put standard weight on weighing device and input the weight value in dialogue window, which value should be same as the weight display on screen.

| Calibrate weight   | 6   | 1.3Kg | A-Level  |
|--|---|-------|----------|
| [Put standard weight in the we<br>hopper and wait until it is stat<br>weight value to calibrate. The<br>shown in the weight display di<br>note.] | ighing<br>ble, then input<br>result will be<br>alog, please |       |          |
| Weight voltage : 0   | .000 mV   |       |          |
| Weight Value : 0   |   |       |          |
| 🕁 Main   | Previous Step   |       | 🔊 Return |

| Calib <sub>I</sub> | Farmar we            | ight | Mir | r:0.000 | Max | :999.99 | A-Level |
|--------------------|----------------------|------|-----|---------|-----|---------|---------|
| [Put st            | 0 <mark>.</mark> 809 |      |     |         |     |         |         |
| weight             | 7                    | 8    |     | 9       |     | Clear   |         |
| note.]             | 4                    | 5    |     | 6       |     | Delete  |         |
| Weigh              | 1                    | 2    |     | 3       |     | Cancel  |         |
|                    | (                    | )    |     |         |     | Confirm | turn    |

#### 4.6.2 Calibration with filling material

1) Zero calibration: Empty hopper and press "Zero calibration" to display zero on screen. Then device will enter gain calibration automatically after zero calibration has been finished 2 seconds later.

2) Gain calibration: After finish filling, press "record current weight" till "OK", then press discharge to weigh the material again. Input the weight value in "weight again" dialogue window for gain calibration.

| Calibrate weight                               | <b>1</b> . (   | 000Kg    | A-Level   |  |  |  |  |  |
|--|----------------|----------|-----------|--|--|--|--|--|
| Step1:Filling and get weight                   |                |          |           |  |  |  |  |  |
| Auto Filling<br>Reco                           | ording Voltage | Clip bag | Discharge |  |  |  |  |  |
| Manual Filling                                 |                |          |           |  |  |  |  |  |
| Ste2 : Input Material actual weight to CAL 0 g |                |          |           |  |  |  |  |  |
| 合 Main   | Previous Step  |          | Return    |  |  |  |  |  |

## 4.7. I/O configure

| Press | I/O Configure | to test and def        | ine I/O: 12 | 2pcs input and 7pc       | s output        |
|-------|---------------|------------------------|-------------|--------------------------|-----------------|
|       | I/O configu   | Iration                | 4           | 0.788Kg                  | A-Level         |
|       |               | Input test             |             | Output test              |                 |
|       | I             | nput meaning<br>define |             | Output meaning<br>define |                 |
|       | 🔒 Main        |                        |             |                          | <b>D</b> Return |

### 4.7.1 Input meaning define:

| No. | Define   | Meaning    |
|-----|----------|------------|
| IN1 | 1 Run    | 0: None    |
| IN2 | 2 E-Stop | 2: E-Stop  |
| IN3 | 3 Stop   | 4: Zeroing |

| IN4  | 4 Zeroing                | 5: Clear alarm<br>6: Select recipe   |
|------|--------------------------|--|
| IN5  | 5 Clear alarm            | 7: Clip/release bag  |
| IN6  | 6 Select recipe          | 9: Manual fine filling   |
| IN7  | 7 Clip/release bag       | 10: Manual coarse filling<br>11: Print grand total   |
| IN8  | 8 Manual discharging     | 12: Upper level<br>13: Lower level   |
| IN9  | 9 Manual fine filling    | 14: Run/Stop (level signal)  |
| IN10 | 10 Manual coarse filling | 16: Manual discharging (level signal)  |
| IN11 | 0 None                   | 17: Manual fine filling (level signal)<br>18: Manual coarse filling (level signal)               |
| IN12 | 0 None                   | <ul><li>19: Push rod to open material gate</li><li>20: Push rod to close material gate</li></ul> |

### 4.7.2 Output meaning define:

| No.                   | Define  | Meaning  |
|-----------------------|---|--|
| OUT1<br>(Manufactory) | 3 Coarse filling  | 0: None  |
| OUT2<br>(Manufactory) | 4 Fine filling  | 1: Run<br>2: Stop  |
| OUT3<br>(Manufactory) | 5 Discharge   | 3: Coarse filling<br>4: Fine filling                                       |
| OUT4<br>(Manufactory) | 14 Push rod to open material gate                       | <ul><li>5: Discharge</li><li>6: Fix weight/finish filling/target</li></ul> |
| OUT5<br>(Manufactory) | OUT5 15 Push rod to close<br>Manufactory) material gate | 7: Over/under tolerance<br>8: Alarm  |
| OUT6                  | 9 Clip bag  | 9: Clip bag  |
| OUT7                  | 1 Run   | 11: Feeding  |
| OUT8                  | 8 Alarm   | 12: Lack material  |
| OUT9                  | 10 Printing code  | 14: Push rod to open material gate   |
| OUT10                 | 13 Batch done   | 15: Push rod to close material gate  |
| OUT11                 | 7 Over/under tolerance                                  | (Output finishing signal after   |
| OUT12                 | 16 Finish packing once                                  | discharging 2 second later)  |

### 4.7.3 Input test

#### Input test

Press

to test connection, which green light instructs ok, but gray not.

| Input Test |               | 0.7 | 88Kg              | A-Level |
|------------|---------------|-----|-------------------|---------|
| IN-1 :     | IN-5 :        |     | IN-9:             |         |
| RUN        | Clear Alarm   |     | Fine feeding(M)   |         |
| IN-2 :     | IN-6 :        |     | IN-10:            |         |
| E-Stop     | Change Recipe |     | Coarse feeding(M) |         |
| IN-3 :     | IN-7:         |     | IN-11 :           |         |
| Stop       | Clip/Loose    |     | NONE              |         |
| IN-4 :     | IN-8 :        |     | IN-12 :           |         |
| Zero       | Discharge(M)  |     | NONE              |         |
| 🔒 Main     |               |     | <b>D</b> I        | Return  |

### 4.7.4 Output test

Press

to test connection, which green instruct ok, but gray not. The user

can press again to check if reset.

Output test

| Output Test    | 0.7              | 88Kg             |  |
|----------------|------------------|------------------|--|
| OUT-1          | OUT-5            | OUT-9            |  |
| Coarse feeding | Actuator close   | Print Code       |  |
| OUT-2          | OUT-6            | OUT-10           |  |
| Fine feeding   | Clip Bag         | Batch Done       |  |
| OUT-3          | OUT-7            | OUT-11           |  |
| Discharge      | run              | O/U Alarm        |  |
| OUT-4          | OUT-8            | OUT-12           |  |
| Actuator open  | <sub>Alarm</sub> | Single pack Done |  |
| 👌 Main         |                  | D Return         |  |

### 4.8. Peripheral device

Peripheral device: Level Sensor, Clipper, Code Printer and Printer.



#### 4.8.1 Level sensor

#### **Dual level sensor**

The device can control feeding function: When both upper and under levels input ineffective, the feeding output effective; When the upper level input effective, the feeding output ineffective. At same time, the device will check if the under level input effective before each filling, if not, the device will output lack material signal and waiting till the under level input effective. But in the whole of filling, the device will not check whether the under level input effective or not.

#### Single level sensor

The device won't control to feed material, only check under level before filling. if not, the device will output lack material signal and waiting till the under level input effective. The filling won't start till the under level input effective before each feeding. But in the whole of filling, the device will not check whether the under level input effective or not.

#### No level

The indicator doesn't control to feed materials and doesn't check whether the under level input effective or not.

#### 4.8.2 Clipper

| No. | Parameter                | Initial | Instruction   |
|-----|--------------------------|---------|---|
| 1   | 0.000 ~<br>99.999 second | 0.5 s   | Delay time after clip bag<br>Finish clip bag after this time                      |
| 2   | 0.000 ~<br>99.999 second | 0.5 s   | Delay time before release bag<br>Once discharge, then release bag after this time |

#### 4.8.3 Code printer

- 1) When the device output clip bag signal and start delay time for printing code at same time, then the device output signal to print code after delay time, the signal will be ineffective after that.
- 2) Printing code is effective in running or stop status.
- 3) Release bag is available in printing code.
- 4) Finish to print code when E-stop signal input.

| No. | Parameter                | Initial | Instruction                           |
|-----|--------------------------|---------|---------------------------------------|
| 1   | ON/OFF                   | OFF     | Code printer switch                   |
| 2   | 0.000 ~<br>99.999 second | 0 s     | Delay time before printing code       |
| 3   | 0.000 ~<br>99.999 second | 2.0 s   | Code printer output effective time    |
| 4   | ON/OFF                   | OFF     | Inhibit to discharge in printing code |

#### 4.8.4 Printer

Please set baud rate and communication format same as printer when serial port 1 or 2 communication protocol is " Serial port printer ".

| No. | Parameter         | Initial | Instruction                            |
|-----|-------------------|---------|--|
| 1   | 16 row / 32 row   | 32 row  | Printing format of 16 rows or 32 rows. |
| 2   | Chinese / English | Chinese | Printing language                      |
| 3   | 0~9               | 3       | Printing lines after one set of data   |
| 4   | ON/OFF            | OFF     | Automatic printing switch              |

#### Automatic printing

The device will print packing details automatically every time if the switch is "ON".

32 row printing format as follows:

 Packing Detail

 ID:
 1

 Run Time: 2000/01/01 80:00

 Unit: 2000/01/01 80:00

 Unit: 2000/01/01 80:00

 Unit: 2000/01/01 80:00

 Total Time: Rec
 Target
 Result

 1.000
 0.995

 3
 1
 1.000
 1.016

 4
 1
 1.000
 1.093

 5
 1
 1.000
 1.009

#### Print total report

Press "PRINT" for total report in stop status.

32 row printing format as follows:

**Total Report** 

| ID:   | 1                |         |
|-------|------------------|---------|
| Time  | 2000/01/01 80:00 |         |
|       |                  |         |
| Total | Times:           | 0       |
| Total | Value:           | 0.000kg |
|       |                  |         |

#### Print recipe report

Press "PRINT" for recipe report in stop status.

32 row printing format as follows:

 Rec. Report

 ID:
 1

 Time:
 2000/01/01 80:00

 ----- ----- 

 Rec.:
 5

 Target:
 0.000

 Rec. Times:
 0

 Rec. Value:
 0.000kg

### 4.9. Data statistics



Recipe statistics : Store all of recipes, which can be zeroing.

**Total statistics :** Store all of total reports, which can be zeroing or printing.

Filling record : Store 50,000pcs records at most, which can be output to U disk.

Parameter configure history : Store revised parameters, such as date, time, data etc.

### 4.10. System function

### 4.10.1 Firmware update

The user can view software version, date and time as follows:

| Firmware Update   |            |              | A-Level  |
|---|------------|--------------|----------|
| Introduction:Keep pressing HMI and Re-power system, till the<br>"Firmware Management" interface come out. Then insert USB<br>drive to update. |            |              |          |
| HMI interface   |            | Logic&Driver |          |
| Version:  | 01.00.00   | Version:     | 00.00.00 |
| Editor Date:  | 2016/10/23 | Editor Date: | 0000/0/0 |
| Editor Time:  | 10:18:43   | Editor Time: | 0:00:00  |
| 🔒 Main  | Model No.  |              | 🤊 Return |

Update tool: U disk

Update file route : Update program must be saved in up\_gm file at the root of U disk. Update file name: HMI interface program must be named DispUp.gm

Logic&Driver program must be named CtrlUp.gm

Note: The power supply do not break in updating.

#### 4.10.2 Backup and reset

Initialize all of parameters : Reset all of parameters to initialization Initialize basic parameters : Reset basic parameters to initialization Initialize calibration parameters : Reset calibration parameters to initialization Initialize recipe parameters : Reset recipe parameters to initialization Initialize peripheral device parameters : Reset peripheral parameters to initialization Initialize self-adaptive parameters : Reset self-adaptive parameters to initialization Initialize communication parameters : Reset communication parameters to initialization Initialize l/O configuration : Reset I/O configuration to initialization Initialize self-adaptive statistics : Reset self-adaptive statistics and renew statistics

#### 4.10.3 Output to USB

The user can output parameter values and statistics to file folder data\_gm in the root of U disk by CSV format as follows:

| ParameterCalib.csv :   | Calibration parameters       |
|------------------------|------------------------------|
| ParameterBasic.csv :   | Basic parameters             |
| ParameterUser.csv :    | User parameters              |
| ParameterIODef.csv :   | IO define                    |
| ParameterComm.csv :    | Communication parameters     |
| ParameterPeri.csv :    | Peripheral parameters        |
| ParameterAdapt.csv :   | Adaptive parameters          |
| ParameterPushrod.csv   | : Push-rod parameters        |
| ParameterHide.csv :    | High degree parameters       |
| StatisticAcc.csv :     | Accumulative statistics      |
| StatisticPacking.csv : | Packing statistics           |
| StatisticPara.csv :    | Parameter revised statistics |

#### 4.10.3 USB input

The user can input parameter file from folder data\_gm in the root of U disk, which file name is same as above.

## 5. Procedure

### 5.1. Procedure

The whole procedure as follows:

- 1. Check target value and material gate before running.
- 2. Delay time before filling.

3. If the self-adaptive function is ON, the user need learn how to set parameters about the leading quantity and free fall on first packaging. And the controller will automatically adapt coarse filling and free fall base on the first packaging.

- 4. Fix weight time after filling finished
- 5. Record the fixed weight as the packing report.
- 6. Dealing with over/under tolerance if need.
- 7. Discharge if clip bag signal is effective.
- 8. Release bag when discharging time is over.

### 5.2. Self-adaptive function

If the self-adaptive function is ON, the controller will automatically set the leading quantity of coarse filling and free fall.

There are two courses on self-adaptive function: self-learn and self-adjust

Self-learn: There is only target weight in a recipe, but no leading quantity of coarse filling and free fall setting, then the controller will self-learn to set these values automatically.

Self-adjust: The controller has got the leading quantity of coarse filling and free fall values, but need adjust the values base on packing procedure in one period, thus to ensure weighing precision in consideration of packing speed.